# Translation

### PATENT COOPERATION TREATY

# PCT Application PCT/JP2003/005449

# **PCT**

# INTERNATIONAL PRELIMINARY EXAMINATION REPORT

(PCT Article 36 and Rule 70)

| Applicant's or agent's file reference   |  |                    |   |  |  |  |
|---|--|--------------------|---|--|--|--|
| PCT03140  | FOR FURTHER ACTION  SeeNotification of Transmittal of International Preliminary Examination Report (Form PCT/IPEA/416) |                    |   |  |  |  |
| International application No.   | International filing date (day)  | month/year)        | Priority date (day/month/year)          |  |  |  |
| PCT/JP03/05449  | 28 April 2003 (28.   | 04.03)             | 26 April 2002 (26.04.02)                |  |  |  |
| International Patent Classification (IPC) or n B25J 5/00, 13/00   | ational classification and IPC   |                    | (                                       |  |  |  |
| Applicant HOND  | A GIKEN KOGYO KAE  | SUSHIKI KA         | AISHA                                   |  |  |  |
| This international preliminary exami<br>and is transmitted to the applicant ac-   | nation report has been prepared cording to Article 36.   | by this Interna    | ational Preliminary Examining Authority |  |  |  |
| 2. This REPORT consists of a total of 3 sheets, including this cover sheet.   |  |                    |   |  |  |  |
| This report is also accompanied by ANNEXES, i.e., sheets of the description, claims and/or drawings which have been amended and are the basis for this report and/or sheets containing rectifications made before this Authority (see Rule 70.16 and Section 607 of the Administrative Instructions under the PCT). |  |                    |   |  |  |  |
| These annexes consist of a total of sheets.   |  |                    |   |  |  |  |
| 3. This report contains indications relating to the following items:  |  |                    |   |  |  |  |
| I Basis of the report   |  |                    |   |  |  |  |
| II Priority   |  |                    |   |  |  |  |
| III Non-establishment of opinion with regard to novelty, inventive step and industrial applicability  |  |                    |   |  |  |  |
| IV Lack of unity of invention   |  |                    |   |  |  |  |
| V Reasoned statement under Article 35(2) with regard to novelty, inventive step or industrial applicability;  |  |                    |   |  |  |  |
| VI Certain documents cited  |  |                    |   |  |  |  |
| VII Certain defects in the international application  |  |                    |   |  |  |  |
| VIII Certain observations on the international application  |  |                    |   |  |  |  |
|   | <u> </u>   |                    |   |  |  |  |
| Date of submission of the demand  | Data of  |                    |   |  |  |  |
| 10 September 2003 (10.09.03)  |  | completion of t    |   |  |  |  |
| - 5 optomoci 2005 (10.05  | .03)   | 01 Oct             | ober 2003 (01.10.2003)                  |  |  |  |
| Name and mailing address of the IPEA/JP   | Authoriz   | Authorized officer |   |  |  |  |
| Facsimile No.   | Telephor   | ne No.             |   |  |  |  |

## INTERNATIONAL PRELIMINARY EXAMINATION REPORT

International application No.

PCT/JP03/05449

| I. Basi:                | s of the report   |
|-------------------------|---|
| 1. With                 | regard to the elements of the international application:*   |
|                         | the international application as originally filed   |
|                         | the description:  |
|                         |   |
|                         | pages, as originally filed  |
|                         | pages, filed with the demand  |
|                         | the claims:   |
|                         | nages   |
|                         | as originally filed   |
|                         | pages, as amended (together with any statement under Article 19   |
|                         | filed with the demand   |
| $\Box$                  | , filed with the letter of  |
|                         | the drawings:   |
|                         | pages, as originally filed  |
|                         | filed with the demand   |
|                         | pages, filed with the letter of   |
| t                       | he sequence listing part of the description:  |
|                         | MO MAN  |
|                         | pages, as originally filed  |
|                         | pages, filed with the letter of, filed with the demand  |
| 3. With prelim          | elements were available or furnished to this Authority in the following language  |
| Replace in this and 70. | the description, pages the claims, Nos the drawings, sheets/fig |

#### INTERNATIONAL PRELIMINARY EXAMINATION REPORT

International application No.

PCT/JP03/05449

| atement                       |        |     |       |
|-------------------------------|--------|-----|-------|
| Novelty (N)                   | Claims | 1-6 | YES   |
|                               | Claims |     | NO    |
| Inventive step (IS)           | Claims | 1-6 | YES   |
|                               | Claims |     | NO    |
| Industrial applicability (IA) | Claims | 1-6 | YES   |
|                               | Claims |     | NO NO |

#### Claims 1, 2, 4 and 6

None of the documents cited in the ISR describes the self-attitude estimating device for a leg type moving robot, in which a new drift correction value is decided such that the deviation between the angular attitude speed obtained by correcting the detected value of an angular attitude speed detecting means using a drift correction value and the estimated angular attitude speed of a slip-less angular attitude speed estimating means becomes close to 0. This constitution is not considered to be obvious to a person skilled in the art either.

#### Claims 3 and 5

None of the documents cited in the ISR describes the self-attitude estimating device for a leg type moving robot, in which the attitude angle of a predetermined region is estimated by integrating the angular attitude speed obtained by correcting at least the detected value of an angular attitude speed detecting means using a drift correction value during the motion of the robot. This constitution is not considered to be obvious to a person skilled in the art either.

Form PCT/ IPEA/409 (Box V) (July 1998)